

**Amendments to the Claims:**

This listing of claims will replace all prior versions, and listings, of claims in the application:

Claim 1 (currently amended): An ion implanter for implanting ions into a target wafer comprising:

an ion source;

an atomic mass unit (AMU) analyzing magnet having a fixed radius  $R_{am}$ ;

an ion extraction voltage source,

a communication interface adapted to monitor implantation parameters including an extraction voltage  $V_E$  of the source of implanting ions and a real-time magnetic flux density  $B$  of a magnetic field of the AMU analyzing magnet generated by a beam current flowing through the analyzing magnet,

an equipment server having a data log, wherein the equipment server is in communication with the ion implanter and is in further communication with the communication interface for monitoring parameters communicated from the ion implanter to the equipment server data log during operation of the ion implanter, wherein the parameters are the  $B$  and the  $V_E$  of the source of implanting ions from the ion implanter, wherein the ion implanter uses a plurality of implantation data to ensure that an AMU of an ion being implanted has less than a .5 AMU difference from an AMU of a desired ion to be implanted, wherein the plurality of implantation data is selected from data relating to a plurality of ions each having predefined AMUs, each of the plurality of ions associated with a monitored  $B$  and a monitored  $V_E$ .

Claim 2 (Canceled)

Appl. No. 10/804,890

Claim 3 (Original): The ion implanter of claim 1 wherein an atomic mass unit of a desired ion being implanted (m) using the implanter is less than 50 atomic mass units.

Claim 4 (Original) The ion implanter of claim 1 further comprising:

means for calculating an estimated real-time radius  $R_e$  of ions being implanted by the ion implanter, wherein the means for calculating being located in at least one of the ion implanter, the equipment server, and a remote device in communication with the equipment server.

Claim 5 (Original): The ion implanter of claim 4, wherein the means for calculating is an arithmetic processor capable of solving an equation for  $R_e$  in accordance with the following equation:

$$R_e = \frac{(m \star V_E)^{(0.5)}}{B}$$

wherein m = the atomic mass of a desired ion to be implanted.

Claim 6 (Currently amended): A method of using an ion implanter, the method comprising the step of:

providing an ion implanter having:

an atomic mass unit analyzing magnet having a radius  $R_{am}$ , and

a communication interface adapted to monitor implantation parameters including an ion extraction voltage  $V_E$  of an ion source of implanting ions and a real-time

Appl. No. 10/804,890

magnetic flux density B of a magnetic field of the AMU  
analyzing magnet; and  
determining in real-time if an ion implanter is implanting a  
desired ion into a target wafer;

determining an offset between the  $R_{am}$  and a real-time  
estimated radius of a circular path of each of a plurality of  
ions having a desired AMU ( $m$ ) being implanted ( $R_e$ );  
providing a predetermined radius tolerance level L having the  
step of

using a plurality of implantation data to ensure that  
an AMU of an ion being implanted has less than a .5 AMU  
difference from an AMU of a desired ion to be implanted,  
wherein the plurality of implantation data is selected from  
data relating to a plurality of ions each having predefined  
AMUs, each of the plurality of ions associated with a  
monitored B and a monitored  $V_E$ ;

and

calculating a plurality of implantation radii  
associated with each of the plurality of ions each having  
predefined AMUs.

Claim 7 (Canceled)

Claim 8 (Canceled)

Claim 9 (Currently amended): The method of claim [[8]] 6, further  
comprising the step of:

determining if an absolute value of the offset between  $R_{am}$   
and  $R_e$  is greater than the predetermined radius tolerance level  
L.

Claim 10 (Canceled)

Appl. No. 10/804,890

Claim 11 (Currently amended): The method of claim [[8]] 6, further comprising the step of:

setting a predefined radius tolerance level equal to .02 cm.

Claim 12 (Currently amended): The method of claim [[7]] 6, further comprising the steps of:

a) calculating the  $R_e$  for each of the plurality of ions being implanted;

b) subtracting  $R_e$  from  $R_{am}$  after calculating  $R_e$  for each of the plurality of ions being implanted;

c) determining an absolute value of the calculated offset between  $R_{am}$  and  $R_e$ .

Claim 13 (Original): The method of claim 9, further comprising the steps of:

using the communication interface to monitor both the  $B$  of the AMU analyzing magnet and the  $V_E$  of the ion source associated with each of the plurality of ions being implanted by the ion implanter;

storing the monitored parameters  $B$  of the AMU analyzing magnet and the  $V_E$  of the ion source associated with each of the plurality of ions being implanted by the ion implanter in the equipment server data log; and

using the stored parameters  $B$  and  $V_E$  to calculate the  $R_e$ .

Appl. No. 10/804,890

Claim 14 (Original): The method of claim 13, wherein the step of using the stored parameters B and  $V_E$  to calculate the  $R_e$  further comprises the step of:

solving for the  $R_e$  in accordance with the following formula

$$R_e = \frac{(m \cdot V_E)^{0.5}}{B}$$

wherein  $m$ =atomic mass unit of a desired ion to be implanted.

Claim 15 (original): The method of claim 9 further comprising:  
signaling an alarm if  $|R_{am}-R_e|>L$ .

Claim 16 (original): The method of claim 9 further comprising the step of:

stopping operation of the ion implanter if  $|R_{am}-R_e|>L$ .

Claim 17 (Currently amended): A method of using an ion implanter, the method comprising the step of:

providing an ion implanter having:

an atomic mass unit analyzing magnet having a radius  $R_{am}$ , and

a communication interface adapted to monitor implantation parameters including an ion extraction voltage  $V_E$  of an ion source of implanting ions and a real-time magnetic flux density B of a magnetic field of the AMU analyzing magnet;

calculating a real-time estimated radius  $R_e$  of a circular path for each of a plurality of ions having a desired AMU ( $m$ ) being implanted;

determining an offset between the  $R_{am}$  and the  $R_e$  a real-time estimated radius of a circular path of each of a plurality of ions having a desired AMU ( $m$ ) being implanted ( $R_e$ );

using a plurality of implantation data to ensure that an AMU of an ion being implanted has less than a .5 AMU difference from an AMU of a desired ion to be implanted, wherein the plurality of implantation data is selected from data relating to a plurality of ions each having predefined AMUs, each of the plurality of ions associated with a monitored B and a monitored  $V_E$ ;

providing a predetermined radius tolerance level  $L$ ;

determining if an absolute value of the offset between  $R_{am}$  and  $R_e$  is greater than the predetermined radius tolerance level  $L$ ; and

recalibrating the ion implanter if  $|R_{am} - R_e| > L$ .

Claim 18 (Original): The method of claim 17, wherein the step of calculating  $R_e$  is performed in accordance with the following equation:

$$R_e = \frac{(m \star V_E)^{(0.5)}}{B}$$

wherein  $m$ =atomic mass unit of a desired ion to be implanted.

Appl.No. 10/804,890

Claim 19 (New): A method of using an ion implanter, the method comprising the step of:

providing an ion implanter having:

an atomic mass unit analyzing magnet having a radius  $R_{am}$ , and

a communication interface adapted to monitor implantation parameters including an ion extraction voltage  $V_E$  of an ion source of implanting ions and a real-time magnetic flux density  $B$  of a magnetic field of the AMU analyzing magnet;

determining in real-time if an ion implanter is implanting a desired ion into a target wafer;

determining an offset between the  $R_{am}$  and a real-time estimated radius of a circular path of each of a plurality of ions having a desired AMU ( $m$ ) being implanted ( $R_e$ );

providing a predetermined radius tolerance level  $L$ ; and

determining if an absolute value of the offset between  $R_{am}$  and  $R_e$  is greater than the predetermined radius tolerance level  $L$ ; and

signaling an alarm if  $|R_{am}-R_e|>L$ .

Claim 20 (New): A method of using an ion implanter, the method comprising the step of:

providing an ion implanter having:

an atomic mass unit analyzing magnet having a radius  $R_{am}$ , and

a communication interface adapted to monitor implantation parameters including an ion extraction voltage  $V_E$  of an ion source of implanting ions and a real-time magnetic flux density  $B$  of a magnetic field of the AMU analyzing magnet;

Appl.No. 10/804,890

determining in real-time if an ion implanter is implanting a desired ion into a target wafer;

determining an offset between the  $R_{am}$  and a real-time estimated radius of a circular path of each of a plurality of ions having a desired AMU ( $m$ ) being implanted ( $R_e$ );

providing a predetermined radius tolerance level  $L$ ; and

determining if an absolute value of the offset between  $R_{am}$  and  $R_e$  is greater than the predetermined radius tolerance level  $L$ ; and

stopping operation of the ion implanter if  $|R_{am}-R_e|>L$ .